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EXISTENCE OF SOLUTIONS OF THE DARBOUX PROBLEM  
FOR PARTIAL DIFFERENTIAL EQUATIONS IN BANACH SPACES

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Abstract: We consider the existence of solutions of the classical Darboux problem for the partial differential equation  $u_{x_1 x_2 x_3}^{(m)} = f(x_1, x_2, x_3, u, u_{x_1}, u_{x_2}, u_{x_3}, u_{x_1 x_2}, u_{x_1 x_3}, u_{x_2 x_3})$  via a fixed point theorem of Sadovskii. Here  $f$  is a continuous function with values in a Banach space satisfying some regularity condition expressed in terms of the measure of noncompactness  $\alpha$ .

Key words: Hyperbolic partial differential equations, Darboux conditions, existence solutions in a Banach space, measure of noncompactness.

Classification: 35A05, 35L15, 34G20.

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1. Introduction. In the present note we consider the following hyperbolic partial differential equation:

$$(*) \quad u_{x_1 x_2 x_3}^{(m)} = f(x_1, x_2, x_3, u, u_{x_1}, u_{x_2}, u_{x_3}, u_{x_1 x_2}, u_{x_1 x_3}, u_{x_2 x_3})$$

with suitable initial boundary conditions of the Darboux type.

Equations of the type (+) (in Euclidean spaces) are considered in papers by Kwapisz, Palczewski and Pawelski [9], Conlan [5], Castellano [3], Palczewski [11], Frasca [8], Chu and Diaz [4], and others. Below, we prove the existence theorem for the case where  $f$  is a continuous function with values in a Banach space satisfying some regularity condition expressed in terms of the measure of noncompactness  $\alpha$ . The proof is based on the fixed point theorem of Sadovskii ([12], Theorem 3.4.4).

2. Notations and preliminaries. Let  $a_i$  ( $i=1,2,3$ ) be positive real numbers. We put  $I_i = [0, a_i]$  and  $V = I_1 \times I_2 \times I_3$ . Throughout this paper  $E$  is a Banach space with norm  $\|\cdot\|$ , and  $f$  is an  $E$ -valued continuous function defined on the product  $\Omega = V \times E \times E^3 \times E^3$ . By  $C(V, E)$  we represent the standard Banach space of all  $E$ -valued continuous functions on  $V$ . Moreover, let  $C^*(V, E)$  denote the class of  $E$ -valued functions  $(x_1, x_2, x_3) \mapsto u(x_1, x_2, x_3)$  continuous on  $V$  to-

gether with their partial derivatives  $u'_{x_1}, u'_{x_2}, u'_{x_3}, u''_{x_1 x_2}, u''_{x_1 x_3}, u''_{x_2 x_3}$  and  $u'''_{x_1 x_2 x_3}$ .

The measure of noncompactness  $\alpha(A)$  of a nonempty bounded subset  $A$  of  $E$  is defined as the infimum of all  $\epsilon > 0$  such that there exists a finite covering of  $A$  by sets of diameter  $\leq \epsilon$ . For the properties of  $\alpha$  the reader is referred to [2],[6],[7],[12].

We shall use in the sequel the following immediate adaptation of Lemma 2.2 of [1] (cf. [10]): If  $P$  is a compact subset of  $V$ , then  $\alpha(\cup\{W(\xi): \xi \in P\}) = \sup\{\alpha(W(\xi)): \xi \in P\}$  for a bounded equicontinuous subset  $W$  of  $C(V, E)$  (here  $W(\xi)$  stands for the set of all  $w(\xi)$  with  $w \in W$ ).

We state the Sadovskii fixed point theorem as follows.

Let  $\mathcal{X}$  be a closed convex subset of  $C(V, E)$ . Let  $\Phi$  be a function which maps each nonempty subset  $W$  of  $\mathcal{X}$  to a real nonnegative  $\Phi(W)$  with (1)  $\Phi(\{w\} \cup W) = \Phi(W)$  for  $w \in \mathcal{X}$ , (2)  $\Phi(\overline{\text{conv } W}) = \Phi(W)$  ( $\overline{\text{conv } W}$  is the closed convex hull of  $W$ ), and (3) if  $\Phi(W) = 0$  then  $\overline{W}$  (the closure of  $W$ ) is compact in  $C(V, E)$ . Assume that  $F$  is a continuous mapping of  $\mathcal{X}$  into itself such that  $\Phi(F[W]) < \Phi(W)$  whenever  $\Phi(W) > 0$ . Then  $F$  has a fixed point in  $\mathcal{X}$ .

3. Formulation of the problem and result. We write  $J_{jk} = I_j \times I_k$  for  $j, k = 1, 2, 3$  with  $j < k$ . Let us determine  $E$ -valued functions  $\sigma_1, \sigma_2$  and  $\sigma_3$  continuous respectively on  $J_{23}, J_{13}$  and  $J_{12}$ , including the second mixed derivatives, and fulfilling the conditions

$$\sigma_1(0, x_3) = \sigma_2(0, x_3), \quad \sigma_1(x_2, 0) = \sigma_3(0, x_2), \quad \sigma_2(x_1, 0) = \sigma_3(x_1, 0)$$

for  $x_i \in I_i$  ( $i=1, 2, 3$ ).

By (PD) we shall denote the problem of finding a function  $u \in C^*(V, E)$  satisfying (+) and the initial conditions

$$u(0, x_2, x_3) = \sigma_1(x_2, x_3), \quad u(x_1, 0, x_3) = \sigma_2(x_1, x_3), \quad u(x_1, x_2, 0) = \sigma_3(x_1, x_2)$$

for all  $(x_j, x_k)$  in  $J_{jk}$ .

We shall write the right side of (+) shortly as  $f(\xi, u, R, Q)$ , where  $\xi = (x_1, x_2, x_3)$  and  $R = (r_1, r_2, r_3)$ ,  $Q = (q_{12}, q_{13}, q_{23})$  with  $r_i(\xi) = u'_{x_i}(\xi)$ ,  $q_{jk}(\xi) = u''_{x_j x_k}(\xi)$ . Moreover, let  $\Theta = (0, 0, 0)$  (here  $0$  is the zero of  $E$ ).

Our result reads as follows.

Theorem. Let  $f$  be uniformly continuous on bounded subsets of  $\Omega$ . Assume that the following conditions hold:

$$1^0 \quad \|f(\xi, u, \Theta, \Theta)\| \leq c_1 + c_2 \|u\| \quad \text{for } \xi \in V \text{ and } u \in E.$$

$$2^0 \quad \|f(\xi, u, R, Q) - f(\xi, u, \bar{R}, \bar{Q})\| \leq \omega\left(\sum_i \|r_i - \bar{r}_i\| + \sum_{j < k} \|q_{jk} - \bar{q}_{jk}\|\right)$$

for  $(\xi, u, R, Q) \in \Omega$  and  $(\xi, u, \bar{R}, \bar{Q}) \in \Omega$ , where  $t \mapsto \omega(t)$  is a nonnegative continuous nondecreasing and subadditive function with  $\omega(0)=0$  only for  $t=0$  and

$$\int_0^\eta \frac{dt}{\omega(t)} = +\infty$$

for  $\eta > 0$ .

3<sup>0</sup>  $\alpha(f[\xi, A]) \leq L \cdot \max\{\alpha(A_i) : 1 \leq i \leq 7\}$  for  $\xi \in V$  and any set  $A$  which is the product of nonempty bounded subsets  $A_i$  of  $E$ .

Under these assumptions, the problem (PD) admits at least one solution on  $V$ .

Proof. Put  $u_{x_1 x_2 x_3}^m = s$ . For the convenience we assume that  $\sigma_i = 0$  for  $i=1, 2, 3$ . Then, (PD) is equivalent to solving the functional-integral equation

$$(*) \quad s(x, y, z) = f(x, y, z, \int_0^x \int_0^y \int_0^z s(t_1, t_2, t_3) dt_1 dt_2 dt_3, \\ \int_0^y \int_0^z s(x, t_2, t_3) dt_2 dt_3, \int_0^x \int_0^z s(t_1, y, t_3) dt_1 dt_3, \\ \int_0^x \int_0^y s(t_1, t_2, z) dt_1 dt_2, \\ \int_0^z s(x, y, t_3) dt_3, \int_0^y s(x, t_2, z) dt_2, \int_0^x s(t_1, y, z) dt_1)$$

in  $C(V, E)$ .

Let  $\lambda = 1 + c_1 + c_2 + 7\omega(1)$ . Let  $\Gamma$  be the set of all  $(\xi, u, R, Q) \in \Omega$  such that  $\|u\| \leq \lambda^{-2} \exp(3\lambda)$ ,  $\|r_i\| \leq \lambda^{-1} \exp(3\lambda)$  and  $\|q_{jk}\| \leq \exp(3\lambda)$  for  $i, j, k = 1, 2, 3$  with  $j < k$ . We set:

$$\tilde{\omega}(\eta) = \sup \{ \|f(\xi, u, R, Q) - f(\bar{\xi}, \bar{u}, \bar{R}, \bar{Q})\| : (\xi, u, R, Q), (\bar{\xi}, \bar{u}, \bar{R}, \bar{Q}) \in \Gamma \text{ with } \|u - \bar{u}\| + \sum_i |x_i - \bar{x}_i| \leq \eta \}$$

and

$$\wp(\eta) = \tilde{\omega}((1 + \exp(3\lambda))\eta) + \omega((2 + \lambda)\exp(3\lambda)\eta)$$

for  $\eta \geq 0$ .

According to the lemma of [11] the equation

$$h(x, y; \eta) = \wp(\eta) + \omega\left(\int_0^x \int_0^y h(t_1, t_2; \eta) dt_1 dt_2 + \int_0^x h(t_1, y; \eta) dt_1 + \int_0^y h(x, t_2; \eta) dt_2\right)$$

has a continuous solution  $h$  such that  $h(x, y, 0) \equiv 0$ . Denote by  $\mathfrak{X}$  the set of all  $w \in C(V, E)$  with

$$\|w(\xi)\| \leq \lambda \cdot \exp\left(\lambda \sum_i x_i\right)$$

and

$$\|w(\xi) - w(\bar{\xi})\| \leq h(\bar{x}_1, \bar{x}_2; |\bar{x}_3 - x_3|) + h(\bar{x}_1, x_3; |\bar{x}_2 - x_2|) + h(x_2, x_3; |\bar{x}_1 - x_1|)$$

for  $\xi = (x_1, x_2, x_3) \in V$  and  $\bar{\xi} = (\bar{x}_1, \bar{x}_2, \bar{x}_3) \in V$ .

Let  $F$  be determined by the right side of (\*). It is easy to verify that  $\mathfrak{X}$  is a closed convex equicontinuous and bounded subset of  $C(V, E)$ , and  $F$  is a continuous mapping of  $\mathfrak{X}$  into itself.

Let  $r > \max(1, L)$ . Define

$$\Phi(W) = \sup \{ \exp(-r\xi) \alpha(W(\xi)) : \xi \in V \}$$

for a nonempty subset  $W$  of  $\mathfrak{X}$ . By properties of  $\alpha$  and Ascoli theorem, our function  $\Phi$  satisfies the conditions (1) - (3) listed in Section 2.

Let  $W$  be a subset of  $\mathfrak{X}$  with  $\Phi(W) > 0$ . To prove the theorem it remains to be shown that  $\Phi(F[W]) < \Phi(W)$ .

Fix  $(x, y, z)$  in  $V$ . Consider the continuous function  $\psi(\xi) = \alpha(W(\xi))$ . Let  $\varepsilon > 0$  be arbitrary and  $\sigma = \sigma(\varepsilon)$  a positive number such that  $\xi' = (t'_1, t'_2, t'_3) \in V$  and  $\xi'' = (t''_1, t''_2, t''_3) \in V$  with  $|t'_i - t''_i| < \sigma$  ( $i=1, 2, 3$ ) implies  $|\psi(\xi') - \psi(\xi'')| < \varepsilon$ . We divide the intervals  $[0, x]$ ,  $[0, y]$  and  $[0, z]$  into  $m$  parts

$$x_0 = 0 < x_1 < \dots < x_m = x, \quad y_0 = 0 < y_1 < \dots < y_m = y, \quad z_0 = 0 < z_1 < \dots < z_m = z$$

in such a way that

$$\max \{ |x_i - x_{i-1}|, |y_i - y_{i-1}|, |z_i - z_{i-1}| : i=1, 2, \dots, m \} < \sigma.$$

Define

$$P_{ijk} = [x_{i-1}, x_i] \times [y_{j-1}, y_j] \times [z_{k-1}, z_k], \quad W_{ijk} = \cup \{ W(\xi) : \xi \in P_{ijk} \}$$

for  $i, j, k=1, 2, \dots, m$ . Moreover, let  $\xi_0$  be a point in  $P_{ijk}$  such that  $\psi(\xi_0) = \sup \{ \psi(\xi) : \xi \in P_{ijk} \}$ .

Denote by  $A_0 = \int_0^x \int_0^y \int_0^z w(t_1, t_2, t_3) dt_1 dt_2 dt_3$  the set of all

$\int_0^x \int_0^y \int_0^z w(t_1, t_2, t_3) dt_1 dt_2 dt_3$  with  $w \in W$ . Applying the integral mean value theorem we obtain

$$\begin{aligned} \alpha(A_0) &\leq \alpha \left( \sum_{i,j,k=1}^m \text{mes}(P_{ijk}) \overline{\text{conv}}(W_{ijk}) \right) = \\ &= \sum_{i,j,k=1}^m \text{mes}(P_{ijk}) \sup \{ \psi(\xi) : \xi \in P_{ijk} \} \leq \sum_{i,j,k=1}^m \int_{P_{ijk}} (|\psi(t_1, t_2, t_3) - \psi(\xi_0)| + \\ &+ \psi(t_1, t_2, t_3)) dt_1 dt_2 dt_3 < \varepsilon xyz + \int_0^x \int_0^y \int_0^z \psi(t_1, t_2, t_3) dt_1 dt_2 dt_3 \leq \\ &\leq \varepsilon xyz + \Phi(W) \int_0^x \int_0^y \int_0^z \exp(r(t_1 + t_2 + t_3)) dt_1 dt_2 dt_3; \end{aligned}$$

therefore

$$\alpha(A_0) < r^{-3} \exp(r(x+y+z)) \cdot \Phi(W).$$

Further, by  $A_i$  ( $i=1, 2, 3$ ) and  $A_{ijk}$  ( $j, k=1, 2, 3$  with  $j < k$ ) we represent

the sets

$$\int_0^y \int_0^z W(x, t_2, t_3) dt_2 dt_3, \int_0^x \int_0^z W(t_1, y, t_3) dt_1 dt_3, \int_0^x \int_0^y W(t_1, t_2, z) dt_1 dt_2$$

and

$$\int_0^z W(x, y, t_3) dt_3, \int_0^y W(x, t_2, z) dt_2, \int_0^x W(t_1, y, z) dt_1,$$

respectively. Arguments analogous to the above imply that

$$\alpha(A_i) < r^{-2} \cdot \exp(r(x+y+z)) \cdot \Phi(W)$$

and

$$\alpha(A_{jk}) < r^{-1} \exp(r(x+y+z)) \cdot \Phi(W).$$

Consequently,

$$\alpha(F[W](x, y, z)) \leq$$

$$\leq L \cdot \max \{ \alpha(A_0), \alpha(A_i), \alpha(A_{jk}) : i, j, k = 1, 2, 3 \text{ with } j < k \} <$$

$$< r^{-1} L \cdot \exp(r(x+y+z)) \cdot \Phi(W)$$

for all  $(x, y, z) \in V$ . This shows that  $\Phi(F[W]) \leq r^{-1} L \cdot \Phi(W)$ . Now, applying Sadovskii's theorem, we infer that  $F$  has a fixed point in  $\mathcal{E}$  and the proof is complete.

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$$\frac{\partial^3 u}{\partial x_1 \partial x_2 \partial x_3} = f(x_1, x_2, x_3, u, \frac{\partial u}{\partial x_1}, \frac{\partial u}{\partial x_2}, \frac{\partial u}{\partial x_3}, \frac{\partial^2 u}{\partial x_1 \partial x_2}, \frac{\partial^2 u}{\partial x_1 \partial x_3}, \frac{\partial^2 u}{\partial x_2 \partial x_3}),$$

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