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# COMMENTATIONES MATHEMATICAE UNIVERSITATIS CAROLINAE

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# A NOTE ON THE EXISTENCE OF MORE THAN ONE SOLUTION FOR ASYMPTOTICALLY LINEAR EQUATIONS

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Abstract: Consider the nonlinear operator equation Lu + N(u) = f with nonlinearity satisfying  $P_0N(x_0) \longrightarrow 0$  as  $\|x_0\| \longrightarrow \infty$  for  $x_0$  in Ker L,  $P_0$  being the projection onto Coker L. Under additional hypotheses we show that this equation has the property that for  $\|P_0f\|$  sufficiently small, it has at least two solutions.

 $\frac{\text{Key words:}}{\text{degree, Leray-Schauder degree, homotopy.}}$ 

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Introduction. Consider the nonlinear operator equation

(A) Lu + N(u) = f

where L is a linear Fredholm map of index zero between Banach spaces X and Y and N is a compact uniformly bounded map of X into Y. Using the notation  $X_0 = \text{Ker L}$ ,  $P_0 = \text{projection onte}$  Coker L, we decompose each x in X into  $x_0 + x_1$  where  $X + X_0 \oplus X_1$  and  $X_1$  is some complement of  $X_0$  in X. We assume

(H.1) Given  $\varepsilon > 0$  and  $k \ge 0$  there exists p > 0 such that if  $\| x_1 \| \le k$  and  $\| x_0 \| \ge p$ ,  $\| P_0 N(x_0 + x_1) \| < \varepsilon$ . In addition, suppose Ker L is one-dimensional and

(H.2) For any M, there exists a number  $R_o$  such that if  $\|x_1\| \le M$  and  $\|x_0\| \ge R_o$   $P_oN(x_0 + x_1)$  and  $P_oN(-x_0 + x_1)$  are of opposite signs.

Then the followin result is known:

Theorem. Assuming (H.1) and (H.2), the equation (A) has a solution for each f in the range of L. Furthermore there is a number c depending on  $P_1f$ , where  $P_1 = I - P_0$  is the projection onto the range of L, such that for  $\|P_0f\| < c(P_1f)$  (A) has a solution.

Examples of boundary-value problems where essentially this abstract result is used can be found in references [1], [2], and [3].

The generalization of this theorem to the case where dim Ker L>1 is easily seen. Let  $\{x_{0i}\}_{i=1,...,n}$  be a fixed basis of unit vectors spanning Ker L and let an arbitrary element of Ker L be denoted by  $a \cdot x_0$  where  $a = (a_1,...,a_n)$   $x_0 = (x_{01},...,x_{0n})$  and  $a \cdot x_0 = a_1x_{01} + ... + a_nx_{0n}$ . Instead of (H.2) assume

- (H.3) For any M there exists a number  $R_o$  such that  $\|x_1\| \le M$  and  $\|a\| \ge R_o$  imply  $P_oN(a \cdot x_o + x_1) \ne 0$  and letting  $\Phi(a) = P_oN(a \cdot x_o)$  be regarded as a map of  $R^n$  into  $R^n$ , assume for  $R \ge R_o$
- (H.4) deg ( $\phi$ ,0, $D_R^n$ )  $\neq$  0 where  $D_R^n$  is the ball of radius R in  $R^n$  and deg is the standard Brouwer degree.

Clearly for the case of a one-dimensional kernel, (H.3) and (H.4) are equivalent to (H.2). The result now reads as follows:

Theorem. Let L and N be as above with N satisfying (H.1), (H.3), and (H.4). Then for each f, there is a number  $c(P_1f)$  such that for  $\|P_0f\| < c(P_1f)$ , (A) has a solution.

A variant of this result has been proved and used by Mawhin in the study of periodic solutions of ordinary vector differential equations. (See [4] and [5]).

In this note we extend the results mentioned above by showing that for  $\|P_0f\|$  sufficiently small and  $\neq 0$ , (A) has in fact at least two solutions.

Section 1. Here we formally state and prove our main result.

Theorem 1. Suppose N satisfies (H.1),(H.3),and (H.4). Then for each f, there exists a number  $c(P_1f)$  such that for  $0 < \|P_0f\| < c(P_1f)$ , equation (A) has at least two solutions. Here  $c(P_1f)$  is the same constant needed in the previously mentioned work.

To prove Theorem 1, using the standard method for semilinear alternative problems, we rewrite (A) as

(1) 
$$F(x_1,a) = 0$$

where  $F: X_1 \times \mathbb{R}^n \longrightarrow X_1 \times \mathbb{R}^n$  is given by

(2) 
$$F(x_1,a) = (x_1 + L^{-1}P_1 [N(a \cdot x_0 + x_1) - f],$$
  
 $P_0N(a \cdot x_0 + x_1) - P_0f)$ 

Here  $P_1$  is the projection onto  $L(X_1)$  and  $L: X_1 \longrightarrow L(X_1)$  has an inverse which we have denoted as  $L^{-1}$ .

Let  $D_k = \{(x_1,a): ||x_1|| + |a| \le k\}$  and let  $S_k$  be its boundary. Then we have

.Lemma 1. There exist constants c and k such that if  $\|P_0f\| < c$ ,  $\deg_{LS}(F,(0,0),D_k) \neq 0$ , where  $\deg_{LS}$  is the Leray-Schauder degree. Furthermore these constants depend on  $P_1f$ .

Proof. Let

(3) 
$$H(x_1,a,t) = (x_1 + tL^{-1}P_1[N(a \cdot x_0 + x_1) - f],$$
  
 $P_0N(a \cdot x_0 + tx_1) - P_0f)$ 

We claim that there exist constants, c, k such that if  $\|P_0f\| < c$ ,  $H(x_1,a,t) \neq 0$  on  $S_k$ . This is easily seen since if the first component of H is zero, by (3),

 $(4) \quad \| \ x_1 \| \leq \| \ L^{-1}P_1 \| \ [\sup_{x \in X} \| N(x) \| \ + \| \ P_1f \|] \equiv M$  and thus by hypothesis, there exists  $R_0$  such that  $P_0N(a \cdot x_0 + x_1) \neq 0$  for  $\| \ x_1 \| \neq M$  and  $\| \ a \| \geq R_0$  so that on the bounded set  $\{ (x_1,a) \colon \| \ x_1 \| \neq M, R_0 \neq \| \ a \| \neq R_0 + M \}$  there is some constant  $\alpha > 0$  such that  $\| \ P_0N(a \cdot x_0 + x_1) \| > \alpha$ . Thus picking  $c = \alpha$ , if  $\| \ P_0f \| < c$  and  $k = M + R_0$  we have  $H(x_1,a,t) \neq 0$ . This gives us that  $H(x_1,a,0)$  is homotopic to  $H(x_1,a,1)$  on  $S_k$ . But  $H(x_1,a,1) = F(x_1,a)$  and

(5) 
$$H(x_1,a,0) = (x_1,P_0N(a \cdot x_0) - P_0f)$$

so that

$$\deg_{IS}(F,(0,0),D_k) = \deg(P_0N(a \cdot x_0) - P_0f,0,D_k^n)$$

$$= \deg(\phi,0,D_k^n) + 0 \text{ by hypothesis (H.4)}.$$

It is easily seen from (4) and the subsequent inequalities that c and k depend on  $P_1f_{\bullet}$ 

Lemma 2. If Pof + 0, there is a k1 depending on Pof

such that  $deg_{LS}(F,(0,0),D_{k_1}) = 0$ .

<u>Proof.</u> Let  $k_1 = M + \wp$  where M is given by equation (4) and  $\wp$  is given by hypothesis (H.1) with  $\varepsilon = \|P_of\|$ .
Thus on  $S_{k_1}$ 

$$G(x_1,a,t) = (x_1 + tL^{-1}P_1[N(a \cdot x_0 + x_1) - f],$$
  
 $tP_0(a \cdot x_0 + x_1) - P_0f)$ 

is a non-vanishing homotopy between  $\Gamma(x_1,a)$  and  $G(x_1,a,0) = (x_1, -P_0f)$ . But clearly

$$\deg_{IS}(G,(0,0),D_{k_1}) = 0$$

since G is not surjective. Thus  $deg_{LS}(F,(0,0),D_{k_1}) = 0$ .

Finally we have

Proof of Theorem 1. Given f, suppose  $\|P_0f\| < c$ , where c is given in Lemma 1. Then there exists k such that  $\deg_{LS}(F,(0,0),D_k) \neq 0$ . But by Lemma 2, there is a  $k_1$  such that  $\deg_{LS}(F,(0,0),D_{k_1}) = 0$ . Therefore there must be a zero of F between  $S_k$  and  $S_{k_1}$ . Thus we conclude that for  $\|P_0f\| < c$ , F must have at least two zeros.

Remark. Note that if  $P_0f = 0$ , the proof of Lemma 2 breaks down, and in fact Prof. Fučík has pointed out to me that the boundary-value problem with f = 0

$$-u'' - u + u(1 + u^2)^{-1} = 0$$

$$u(0) = u(w) = 0$$

satisfying (H.1) and (H.2), is uniquely solvable.

I would like to express my thanks to Prof. Fučík for the current formulation of hypothesis (H.1).

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