

Werk

Label: Article

Jahr: 1971

PURL: https://resolver.sub.uni-goettingen.de/purl?316342866_0012|log14

Kontakt/Contact

[Digizeitschriften e.V.](#)
SUB Göttingen
Platz der Göttinger Sieben 1
37073 Göttingen

✉ info@digizeitschriften.de

ON SOLUTIONS OF NONAUTONOMOUS LINEAR DELAYED DIFFERENTIAL EQUATIONS WHICH ARE DEFINED AND BOUNDED FOR $t \rightarrow -\infty$

Jaroslav KURZWEIL, Praha

Let M_n be the space of real square matrices of order n , \mathbb{R} - the real line, \mathbb{R}^+ - the positive half-line (closed), \mathbb{R}^- - the negative half-line, $A: \mathbb{R}^- \rightarrow M_n$, $B: \mathbb{R}^- \rightarrow M_n$ locally integrable. For $y \in \mathbb{R}^n$ denote by $|y|$ the Euclidean norm of y and for $C \in M_n$ put $|C| = \sup_{|y| \leq 1} |Cy|$. For $\gamma \in \mathbb{R}^+$ let $Z(\gamma)$ be the set of such solutions $x: \mathbb{R}^- \rightarrow \mathbb{R}^n$ of

$$(1) \quad \frac{dx}{dt}(t) = A(t)x(t) + B(t)x(t-1)$$

that

$$(2) \quad \sup_{t \leq 0} e^{\gamma t} |x(t)| < \infty.$$

Obviously $Z(\gamma)$ is a linear manifold.

Theorem. Assume that $|B|^2$ is locally integrable and that

$$(3) \quad \sup_{t \leq 0} \int_{t-1}^t |A(\tau)| d\tau < \infty, \quad \sup_{t \leq 0} \int_{t-1}^t |B(\tau)|^2 d\tau < \infty.$$

Then the dimension of $Z(\gamma)$ is finite. Moreover, there exists $\Theta: (\mathbb{R}^+)^3 \rightarrow \mathbb{R}^+$ such that if

$$(4) \sup_{t \geq 0} \int_{t-1}^t |A(\tau)| d\tau \leq a, \sup_{t \geq 0} \int_{t-1}^t |B(\tau)|^2 d\tau \leq b^2,$$

then

$$(5) \dim Z(\gamma) \leq \Theta(a, b, \gamma).$$

Note 1. $\Theta(a, b, \gamma)$ may be calculated (of course not the best one). Thus it may be shown that

$$(i) \dim Z(\gamma) \leq n \quad \text{if} \\ e^{(n+1)\gamma} [1 + 4e^{2a} \max(1, b^2)]^{n/2} e^a b < 1,$$

$$(ii) \dim Z(\gamma) \leq n + 1 \quad \text{if} \\ e^{(n+2)\gamma} [1 + 4e^{2a} \max(1, b^2)]^{n/2} e^{2a} b^2 < 1,$$

$$(iii) \text{ if } e^a b \geq 1 \quad \text{and } e^\gamma (1 + a e^a) b \rightarrow \infty,$$

then

$$\Theta(a, b, \gamma) \approx 2n e \pi^{-2} e^{2\gamma} (1 + a e^a)^2 b^2.$$

Note 2. The above theorem is related to applications of Theory of Invariant Manifolds to Delayed Differential Equations (cf. [1],[2],[3]). Let us review some results which may be obtained for (1). For this purpose extend A and B to \mathbb{R} putting $A(t) = 0 = B(t)$ for $t > 0$.

Proposition. Assume that A fulfils (4) and that B instead of (4) fulfils

$$(6) \sup_t \int_{t-1}^t |B(\tau)| d\tau \leq \beta$$

and that there exists $L > 0$ such that

$$(7) e^a (e^a + L)^2 \beta \leq L,$$

$$(8) (e^a + 1) e^a (e^a + L) \beta < 1.$$

Let U be a fundamental matrix of

$$(9) \quad \frac{dx}{dt}(t) = A(t)x(t).$$

Then there exists $Q : \mathbb{R}^* \rightarrow M_n$, continuous,
 $|Q(t)| \leq L$ for $t \in \mathbb{R}$ such that every solution of

$$(10) \quad \frac{dx}{dt}(t) = (A(t) + B(t)[U(t-1)U^{-1}(t) + Q(t)])x(t)$$

fulfils (1). Moreover, solutions of (10) belong to $Z(\gamma)$

with $\gamma = a + \log [1 + \beta(e^a + L)]$ (so that

$\dim Z(\gamma) \geq n$).

$$\text{As } \int_{t-1}^t |B(\tau)| d\tau \leq \left(\int_{t-1}^t |B(\tau)|^2 d\tau \right)^{1/2},$$

Proposition may be applied, if B fulfils (4) and if (7) and (8) hold, β being replaced by ℓ .

Fix a and choose L , e.g. $L = e^a$. Find such a ℓ that (7) and (8) are fulfilled for β being replaced by ℓ and that the inequality in (i), Note 1 is fulfilled with $\gamma \geq a + \log [1 + \ell(e^a + L)]$.

Then it may be concluded that $\dim Z(\gamma) = n$ (provided that A and B fulfil (4)).

References

- [1] J. KURZWEIL: Invariant manifolds for flows, Differential equations and dynamical systems, Proceedings of an Internat. Symposium, Academic Press 1967, 431-468.
- [2] A. HALANAY, J. KURZWEIL: A theory of invariant manifolds for flows, Revue Roumaine de mathématiques pures et appliquées, 13(1968), 1079-1087.

[3] J. KURZWEIL: Invariant manifolds I, Comm.Math.Univ.
Carolinae 11(1970), 309-336.

(Oblatum 13.10.1970)

Matematický ústav ČSAV

Žitná 25

Praha 1

Československo