

Werk

Label: Article

Jahr: 1975

PURL: https://resolver.sub.uni-goettingen.de/purl?31311157X_0100|log68

Kontakt/Contact

[Digizeitschriften e.V.](#)
SUB Göttingen
Platz der Göttinger Sieben 1
37073 Göttingen

✉ info@digizeitschriften.de

A GENERALIZATION OF THE TORSION FORM

IVAN KOLÁŘ, Brno

(Received May 5, 1974)

The well-known torsion form of a linear connection on an n -dimensional manifold M is the exterior covariant derivative of the canonical \mathbf{R}^n -valued form φ of the bundle of linear frames. As a natural generalization of φ , we have introduced the canonical $(\mathbf{R}^n \oplus \mathfrak{g})$ -valued form θ of the first prolongation $W^1(P)$ of an arbitrary principal fibre bundle $P(B, G)$, $n = \dim B$, [5]. In a similar way, we define the torsion form of a connection on $W^1(P)$ to be the exterior covariant derivative of θ . This concept generalizes also the torsion form of a linear connection of higher order in the sense of YUEN, [11]. Using a result by ŠVEC, we find the structure equations of θ . We also deduce that the connections on $W^1(P)$ are in a one-to-one correspondence with certain reductions of the second semi-holonomic prolongation $\overline{W}^2(P)$ of P , and a connection on $W^1(P)$ is without torsion if and only if the corresponding reduction is holonomic. In the special case of a linear connection, these results were established by KOBAYASHI, [3], and LIBERMANN, [8]. In conclusion, we treat the prolongation $p(\Gamma, A)$ of a connection Γ on P with respect to a linear connection A on the base manifold, [7], and we find a necessary and sufficient geometric condition for $p(\Gamma, A)$ to be without torsion. — Standard terminology and notation of the theory of jets are used throughout the paper, see, e.g., [10]. Our investigations are carried out in the category C^∞ .

1. Let G and H be two Lie groups. Assume that every $g \in G$ determines an automorphism $\tilde{g} : H \rightarrow H$ such that the mapping $g \mapsto \tilde{g}$ is a right action of G on H . Consider the corresponding semi-direct product $G \overline{\times} H$, i.e., the multiplication in $G \overline{\times} H$ is given by

$$(1) \quad (g_1, h_1)(g_2, h_2) = (g_1 g_2, \tilde{g}_2(h_1) h_2), \quad g_1, g_2 \in G, \quad h_1, h_2 \in H.$$

We have natural injections $G \rightarrow G \overline{\times} H, g \mapsto (g, e_H)$ and $H \rightarrow G \overline{\times} H, h \mapsto (e_G, h)$. In this sense, Lie algebras \mathfrak{g} and \mathfrak{h} of G and H form two complementary subspaces of the Lie algebra of $G \overline{\times} H$. One verifies directly that

$$(2) \quad \text{ad}(g, e_H)(e_G, h) = (e_G, \tilde{g}^{-1}(h)).$$

Consider further a principal fibre bundle $P(B, G, \pi)$. Introduce a projection $P \times H \rightarrow B$, $(u, h) \mapsto \pi(u)$, $u \in P$, $h \in H$, and define a right action of $G \overline{\times} H$ on $P \times H$ by

$$(3) \quad (u, h_1)(g, h_2) = (ug, \tilde{g}(h_1)h_2).$$

Lemma 1. $P \times H$ with action (3) is a principal fibre bundle $(P \times H)(B, G \overline{\times} H)$.

Proof is straightforward.

Obviously, $P \approx P \times \{e_H\}$ is a reduction of $P \times H$ to the subgroup $G \subset G \overline{\times} H$. In view of (2), we can apply the result by Švec, [9], p. 572. This proves

Lemma 2. Let $\omega = \omega_1 \oplus \omega_2$ be a $(\mathfrak{g} \oplus \mathfrak{h})$ -valued connection form on $P \times H$ and $\bar{\omega}_1$ or $\bar{\omega}_2$ the restriction of ω_1 or ω_2 to P , respectively. Then $\bar{\omega}_1$ is a connection form and $\bar{\omega}_2$ is an \mathfrak{h} -valued tensorial form of type $\text{ad } G$. Conversely, if $\bar{\omega}$ is a connection form on P and φ is an \mathfrak{h} -valued tensorial form of type $\text{ad } G$ on P , then there is a unique connection form on $P \times H$ such that its restriction to P is $\bar{\omega} \oplus \varphi$.

In particular, let ϱ be a representation of G on a finite dimensional vector space V . For $A \in \mathfrak{g}$, $A = j_0^1 \gamma(t)$ and $B \in V$, we set

$$(4) \quad A \cdot B = \lim_{t \rightarrow 0} \frac{1}{t} [\varrho(\gamma(t))(B) - B].$$

This defines a bilinear map $\mathfrak{g} \times V \rightarrow V$, $(A, B) \mapsto A \cdot B$. Since V is an Abelian group and $g \mapsto \varrho(g^{-1})$ is a right action of G on V , we can construct the semi-direct product $G \overline{\times} V$. Let ω be a connection form on P and φ a V -valued tensorial 1-form of type ϱ on P . We have the situation of Lemma 2 and one verifies easily that formula (2.23) of [9] is equivalent to the following

Proposition 1. It is

$$(5) \quad d\varphi = -\omega \cdot \varphi + D\varphi,$$

where $D\varphi$ is the covariant exterior derivative of φ with respect to ω and $\omega \cdot \varphi$ means the 2-form on P defined by the extension of bilinear map (4).

2. Consider now the first prolongation $W^1(P)$ of a principal fibre bundle $P(B, G)$, [5]. We recall that $W^1(P) = H^1(B) \oplus J^1P$ is a principal fibre bundle over B with structure group $G_n^1 = L_n^1 \overline{\times} T_n^1(G)$ (= the semi-direct product with respect to the action $S \mapsto SY$ of L_n^1 on $T_n^1(G)$, $Y \in L_n^1$, $S \in T_n^1(G)$), $n = \dim B$. There are two canonical principal fibre bundle homomorphisms $\beta : W^1(P) \rightarrow P$ and $\lambda : W^1(P) \rightarrow H^1(B)$. In [5], we have introduced the canonical $(\mathbf{R}^n \oplus \mathfrak{g})$ -valued form θ of $W^1(P)$ and we have deduced that θ is a pseudotensorial form of type ϱ , where the representation ϱ of G_n^1 on $\mathbf{R}^n \oplus \mathfrak{g}$ is defined by formula (12) of [5]. If Γ is a connection on $W^1(P)$, then the covariant absolute derivative $D\theta$ of θ will be called the torsion of Γ .

Remark 1. If we consider the trivial one-element group $G = \{e\}$ and the trivial bundle $B \times \{e\}$, then $W^1(B \times \{e\}) = H^1(B)$ and θ coincides with the canonical \mathbf{R}^n -valued form of $H^1(B)$. Hence we get really a generalization of the linear case.

Remark 2. Using the identification $\tilde{H}^r(B) \approx W^1(\tilde{H}^{r-1}(B))$ of [5], we obtain the inclusion $\tilde{H}^r(M) \subset W^1(\tilde{H}^{r-1}(M))$. Further, the restriction of the canonical form of $W^1(\tilde{H}^{r-1}(M))$ to $\tilde{H}^r(M)$ is the canonical form of $\tilde{H}^r(M)$. In this interpretation, our results generalize the investigation of the torsion form of a higher order linear connection by Yuen, [11].

By (4), ϱ determines a bilinear map $\mathfrak{g}_n^1 \times (\mathbf{R}^n \oplus \mathfrak{g}) \rightarrow \mathbf{R}^n \oplus \mathfrak{g}$, $(A, B) \mapsto A \cdot B$. According to [5], we have a decomposition $\mathfrak{g}_n^1 = \mathfrak{g} \oplus (\mathbf{R}^n \otimes \mathbf{R}^{n*}) \oplus (\mathfrak{g} \otimes \mathbf{R}^{n*})$. Hence we can write every $A \in \mathfrak{g}_n^1$ as $A = A_1 + A_2 + A_3$, $A_1 \in \mathfrak{g}$, $A_2 \in \mathbf{R}^n \otimes \mathbf{R}^{n*}$, $A_3 \in \mathfrak{g} \otimes \mathbf{R}^{n*}$, and every $B \in \mathbf{R}^n \oplus \mathfrak{g}$ as $B = B_0 + B_1$, $B_0 \in \mathbf{R}^n$, $B_1 \in \mathfrak{g}$. The same notation will be used for \mathfrak{g}_n^1 -valued and $(\mathbf{R}^n \oplus \mathfrak{g})$ -valued forms. Let $\langle, \rangle : \mathbf{R}^n \times (\mathbf{R}^n \otimes \mathbf{R}^{n*}) \rightarrow \mathbf{R}^n$, $\langle, \rangle_G : \mathbf{R}^n \times (\mathfrak{g} \otimes \mathbf{R}^{n*}) \rightarrow \mathfrak{g}$ be tensor contractions and $[,]$ the bracket of \mathfrak{g} . By direct evaluation, we obtain the formula for $A \cdot B$

$$(6) \quad \begin{aligned} (A \cdot B)_0 &= \langle A_2, B_0 \rangle, \\ (A \cdot B)_1 &= [A_1, B_1] + \langle A_3, B_0 \rangle_G. \end{aligned}$$

Proposition 2. (Structure equations of θ .) Let ω be a connection form on $W^1(P)$. Then we have

$$(7) \quad d\theta = -\omega \cdot \theta + \frac{1}{2}[\omega_1, \omega_1] + D\theta,$$

where the \mathfrak{g} -valued form $[\omega_1, \omega_1]$ is considered an $(\mathbf{R}^n \oplus \mathfrak{g})$ -valued form with zero component in \mathbf{R}^n .

Proof is based on Proposition 1. However, θ is not horizontal. That is why we shall first consider the tensorial form $\tilde{\theta} = \theta h$, i.e. $\tilde{\theta}(X) = \theta(hX)$, where hX means the horizontal component of the vector $X \in T(W^1(P))$. By Proposition 1,

$$(8) \quad \begin{aligned} d\tilde{\theta}_0 &= -\langle \omega_2, \tilde{\theta}_0 \rangle + D\tilde{\theta}_0, \\ d\tilde{\theta}_1 &= -[\omega_1, \tilde{\theta}_1] - \langle \omega_3, \tilde{\theta}_0 \rangle_G + D\tilde{\theta}_1. \end{aligned}$$

Further, let Y be a vertical vector on $W^1(P)$, which is the value of the fundamental vector field determined by an element $A \in \mathfrak{g}_n^1$. By the definition of θ , [5], we have $\theta(Y) = A_1$. Hence $\theta = \tilde{\theta} + \omega_1$, where the \mathfrak{g} -valued form ω_1 is considered an $(\mathbf{R}^n \oplus \mathfrak{g})$ -valued form with zero component in \mathbf{R}^n . Substituting it into (8), we obtain

$$(9) \quad \begin{aligned} d\theta_0 &= -\langle \omega_2, \theta_0 \rangle + D\theta_0, \\ d\theta_1 &= -[\omega_1, \theta_1] - \langle \omega_3, \theta_0 \rangle_G + [\omega_1, \omega_1] + d\omega_1 - D\omega_1 + D\theta_1. \end{aligned}$$

According to the structure equations of ω , it is

$$(10) \quad d\omega_1 = -\frac{1}{2}[\omega_1, \omega_1] + D\omega_1.$$

Comparing (9) and (10), we deduce (7), QED.

3. We have remarked in [4] that a connection on a principal fibre bundle $P(B, G)$ can be defined as a G -invariant cross section $P \rightarrow J^1P$. Consider a connection Γ on $W^1(P)$ in such a form, i.e. $\Gamma : W^1(P) \rightarrow J^1W^1(P)$. We have $J^1W^1(P) = J^1(H^1(B) \oplus J^1P) = J^1H^1(B) \oplus J^2P$. There is a standard identification $\varkappa : J^1H^1(B) \approx \bar{H}^2(B)$ sending an element $Z = j_x^1\varphi \in J^1H^1(B)$, $\varphi(x) = j_0^1\psi(y)$ into $\varkappa(Z) = j_0^1[\varphi(\psi(y))t_y^{-1}] \in \bar{H}^2(B)$, where $t_y : \mathbf{R}^n \rightarrow \mathbf{R}^n$ is the translation $z \mapsto z + y$. On the other hand, the second semi-holonomic prolongation $\bar{W}^2(P)$ of P is equal to $\bar{H}^2(B) \oplus J^2P$, [5], so that the jet inclusion $J^2P \subset J^2P$ induces the inclusion $\bar{W}^2(P) \subset J^1W^1(P)$. We define the reduction $R(\Gamma) \subset \bar{W}^2(P)$ determined by a connection $\Gamma : W^1(P) \rightarrow J^1W^1(P)$ to be the intersection

$$(11) \quad R(\Gamma) = \Gamma(W^1(P)) \cap \bar{W}^2(P).$$

Consider the induced connection $\Gamma_0 = \beta_*\Gamma : P \rightarrow J^1P$. We recall, [6], that $R(\Gamma_0) := H^1(B) \oplus \Gamma_0(P)$ is a reduction of $W^1(P)$ to the subgroup $L_n^1 \times i_1(G) \subset G_n^1$, where $i_1 : G \rightarrow T_n^1(G)$ is the canonical injection $g \mapsto j_0^1\hat{g}$, \hat{g} being the constant mapping $x \mapsto g$, $x \in \mathbf{R}^n$.

Lemma 3. *We have $\Gamma(u) \in R(\Gamma)$ if and only if $u \in R(\Gamma_0) \subset W^1(P)$.*

Proof. Let $\Gamma(u) = j_x^1\varphi$, where $\varphi = (\varphi_1, \varphi_2)$ is a local cross section of $H^1(B) \oplus J^1P$. The condition for $j_x^1\varphi_2$ to be semi-holonomic is $\varphi_2(x) = j_x^1(j_1^0\varphi_2) = j_x^1(\beta\varphi) = \Gamma_0(j_1^0u)$, where $j_1^0 : J^1P \rightarrow P$ is the jet projection. This is equivalent to $u \in R(\Gamma_0)$, QED.

Consider further the canonical injections $i_2 : G \rightarrow T_n^2(G)$, $g \mapsto j_0^2\hat{g}$ and $i : L_n^1 \rightarrow L_n^2$. The last mapping can be geometrically described as follows. If $Y \in L_n^1$, $Y = j_0^1\psi(y)$, then

$$(12) \quad i(Y) = j_0^1[t_{\psi(y)}Yt_y^{-1}].$$

Our next assertion generalizes a result by LIBERMANN, [8].

Proposition 3. *$R(\Gamma)$ is a reduction of $\bar{W}^2(P)$ to the subgroup $i(L_n^1) \times i_2(G) \subset L_n^2 \times T_n^2(G) = \bar{G}_n^2$. Conversely, every reduction Q of $\bar{W}^2(P)$ to $i(L_n^1) \times i_2(G)$ determines a unique connection $\Gamma(Q)$ on $W^1(P)$ such that $Q = R(\Gamma(Q))$.*

Proof. Put $\Gamma(v, \Gamma_0(u)) = (Z, T) \in J^1H^1(B) \oplus J^2P$, $u \in P$, $v \in H^1(B)$, and $Z =$

$= j_x^1 \varphi, T = j_x^1 \sigma$. Starting from the fact that Γ is G_n^1 -invariant and using the formula for the action of G_n^1 on $W^1(P)$, [5], we find

$$(13) \quad \tau(vY, \Gamma_0(ug)) = j_x^1[\varphi(y) Y, \sigma(y) \cdot (i_1(g) Y^{-1} \varphi^{-1}(y))],$$

$Y \in L_n^1, g \in G$. On the other hand, the formula for the action of \bar{G}_n^2 on $\bar{W}^2(P)$ yields

$$(\kappa(Z), T) (i(Y), i_2(g)) = (\kappa(Z) i(Y), T \cdot (i_2(g) i(Y)^{-1} \kappa(Z)^{-1})),$$

see [5]. The relation $\kappa(Z) i(Y) = j_x^1[\varphi(y) Y]$ is known from the linear case, [8]. Further, the injection $i_2 : G \rightarrow T_n^2(G)$ can be also expressed as $g \mapsto j_0^1[i_1(g) t_y^{-1}]$. Then we find easily $i_2(g) i(Y)^{-1} \kappa(Z)^{-1} = j_x^1(i_1(g) Y^{-1} \varphi^{-1}(y))$. Comparing with (13), we conclude that $R(\Gamma)$ is a reduction to the subgroup $i(L_n^1) \times i_2(G)$. The converse assertion can be proved quite similarly, QED.

We shall also need another geometric characterization of $R(\Gamma)$. We recall that a semi-holonomic connection of the second order on P is a G -invariant cross section $P \rightarrow \bar{J}^2 P$, [4]. For every $(v, u) \in H^1(B) \oplus P$, define $\mu(\Gamma)(v, u) = p_2(\Gamma(v, \Gamma_0(u)))$, where $p_2 : J^1 W^1(P) \rightarrow \bar{J}^2 P$ is the product projection. According to Lemma 3, the values of $\mu(\Gamma)$ lie in $\bar{J}^2 P$.

Lemma 4. For every $Y \in L_n^1$, it is $\mu(\Gamma)(v, u) = \mu(\Gamma)(vY, u)$.

Proof. Let $\Gamma(v, \Gamma_0(u)) = j_x^1(\varphi_1(y), \varphi_2(y))$. Since Γ is invariant, we have $\Gamma(vY, \Gamma_0(u)) = j_x^1(\varphi_1(y) Y, \varphi_2(y))$, QED.

Thus, we may consider $\mu(\Gamma)$ to be a cross section $P \rightarrow \bar{J}^2 P$.

Proposition 4. $\mu(\Gamma) : P \rightarrow \bar{J}^2 P$ is a semi-holonomic connection of the second order on P .

Proof. We have to prove that $\mu(\Gamma)$ is G -invariant. But this is a simple consequence of Proposition 3, QED.

Denote by $\Lambda = \lambda_* \Gamma$ the induced connection on $H^1(B)$ and by $R(\Lambda)$ the corresponding reduction of $\bar{H}^2(B)$. Our previous consideration implies

$$(14) \quad R(\Gamma) = R(\Lambda) \oplus \mu(\Gamma)(P).$$

4. The following assertion generalizes a result by Kobayashi, [3].

Proposition 5. It is $R(\Gamma) \subset W^2(P)$ if and only if $D\theta = 0$.

Proof. We first deduce a lemma. Since $\bar{W}^2(P) \subset W^1(W^1(P))$, every $U \in \bar{W}^2(P)$ determines a mapping $\tilde{U}^{-1} : T_u(W^1(P)) \rightarrow \mathbf{R}^n \oplus \mathfrak{g}_n^1$, where $u \in W^1(P)$ is the underlying jet of U , [5]. Denote by $q : W^1(P) \rightarrow B$ the bundle projection.

Lemma 5. Let M be a submanifold of $W^1(P)$ such that $q \mid M$ is a submersion.

Let $\sigma : M \rightarrow \overline{W}^2(P)$ be a cross section and θ the $(\mathbf{R}^n \oplus \mathfrak{g}_n^1)$ -valued form on M constructed by means of σ , i.e. $\theta | T_u(M) = \widetilde{\sigma}(u)^{-1} | T_u(M)$, $u \in M$. Then $\sigma(M) \subset W^2(P)$ if and only if

$$(15) \quad d\theta_0 = -\langle \theta_2, \theta_0 \rangle, \quad d\theta_1 = -\frac{1}{2}[\theta_1, \theta_1] - \langle \theta_3, \theta_0 \rangle_G.$$

Proof of Lemma 5. For $M = W^1(P)$, the assertion was deduced by direct evaluation by DEKRÉT, [1]. Using the coordinates of [5] or [1], we have local coordinates a_{ij}^λ on fibred manifold $\overline{W}^2(P) \rightarrow W^1(P)$, $i, j, \dots = 1, \dots, n$, $\lambda = 1, \dots, n + \dim G$. The subspace $W^2(P) \subset \overline{W}^2(P)$ is characterized by $a_{ij}^\lambda = a_{ji}^\lambda$. Consider (locally) a cross section $\sigma_1 : W^1(P) \rightarrow \overline{W}^2(P)$ extending σ . Let σ_1 be given by some functions f_{ij}^λ , so that σ is given by $f_{ij}^\lambda = f_{ij}^\lambda | M$. Denote by $\tilde{\theta}$ the $(\mathbf{R}^n \oplus \mathfrak{g}_n^1)$ -valued form on $W^1(P)$ constructed by means of σ_1 . The evaluations by Dekrét imply (in coordinates)

$$(16) \quad \begin{aligned} d\tilde{\theta}^i &= \tilde{\theta}^j \wedge \tilde{\theta}_j^i + f_{jk}^i \tilde{\theta}^j \wedge \tilde{\theta}^k, \\ d\tilde{\theta}^\alpha &= -\frac{1}{2}c_{\beta\gamma}^\alpha \tilde{\theta}^\beta \wedge \tilde{\theta}^\gamma + \tilde{\theta}^i \wedge \tilde{\theta}_i^\alpha + f_{jk}^\alpha \tilde{\theta}^j \wedge \tilde{\theta}^k, \end{aligned}$$

$\alpha = n + 1, \dots, n + \dim G$. Restricting (16) to M , we find that (15) holds if and only if $f_{ij}^\lambda = f_{ij}^\lambda$, thus proving Lemma 5.

We are now in position to prove Proposition 5. Denote by $\tilde{\omega} = \tilde{\omega}_1 \oplus \tilde{\omega}_2 \oplus \tilde{\omega}_3$ or $\tilde{\theta} = \tilde{\theta}_0 \oplus \tilde{\theta}_1$ the restriction of the connection form or the canonical form θ to $R(\Gamma)$, respectively. By the definition of $R(\Gamma)$ and by Lemma 3, it is $\tilde{\omega}_1 = \tilde{\theta}_1$ and $\tilde{\theta}_0 \oplus \tilde{\theta}_1 \oplus \tilde{\omega}_2 \oplus \tilde{\omega}_3$ is the $(\mathbf{R}^n \oplus \mathfrak{g}_n^1)$ -valued form constructed by means of the cross section $\Gamma | R(\Gamma_0)$. According to (7), we have

$$\begin{aligned} d\tilde{\theta}_0 &= -\langle \tilde{\omega}_2, \tilde{\theta}_0 \rangle + D\tilde{\theta}_0, \\ d\tilde{\theta}_1 &= -\frac{1}{2}[\tilde{\theta}_1, \tilde{\theta}_1] - \langle \tilde{\omega}_3, \tilde{\theta}_0 \rangle_G + D\tilde{\theta}_1. \end{aligned}$$

Then Proposition 5 follows from Lemma 5, QED.

5. In particular, if Γ is a connection on P and A is a linear connection on B , then the prolongation $p(\Gamma, A)$ of Γ with respect to A is an interesting special connection on $W^1(P)$, [7].

Proposition 6. Connection $p(\Gamma, A)$ is without torsion if and only if Γ is integrable and A is without torsion.

Proof. As a direct consequence of the definition, we have $\mu(p(\Gamma, A)) = \Gamma'$, where Γ' means the prolongation of Γ in the sense of Ehresmann, [2]. According to (14), it is $R(p(\Gamma, A)) = R(A) \oplus \Gamma'(P)$. By a result by Kobayashi, [3] (or as a special case of Proposition 5), $R(A) \subset H^2(B)$ if and only if A is without torsion. On the other hand, according to Ehresmann, [2], $\Gamma'(P) \subset J^2P$ if and only if Γ is integrable. By Proposition 5 we prove our assertion, QED.