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**ON THE ASYMPTOTIC BEHAVIOUR OF SOLUTIONS
 OF FUNCTIONAL DIFFERENTIAL EQUATIONS
 WITH DEVIATING ARGUMENT**

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Let \mathbb{R}^n denote the n — dimensional vector space with norm $|\cdot|$, $\mathbb{R}_- = (-\infty, 0]$, $\mathbb{R}_+ = [0, \infty)$ and $\mathbb{R} = (-\infty, \infty)$. Let C be the Banach space of all continuous and bounded functions $g: \mathbb{R}_- \rightarrow \mathbb{R}^n$ with the sup-norm $\|\cdot\|$. Let $\psi: \mathbb{R}_+ \rightarrow (0, \infty)$ be a nondecreasing continuous function.

Let D be the vector space of all continuous functions $g: \mathbb{R} \rightarrow \mathbb{R}^n$ which are bounded in \mathbb{R}_- and ψ — bounded in \mathbb{R}_+ (i.e. $\psi(t)^{-1}|g(t)|$ is bounded on \mathbb{R}_+).

Let $\{I_k\}_{k=1}^\infty$ be a sequence of compact intervals such that $\bigcup_{k=1}^\infty I_k = \mathbb{R}_+$, where $I_k = [0, k]$ and for every $k \in \mathbb{N}$ we have $I_k \subset I_{k+1} \subset \mathbb{R}_+$.

Let F be a Fréchet space of all continuous functions $g: \mathbb{R}_+ \rightarrow \mathbb{R}^n$ with a locally convex topology defined by systems of seminorms

$$p_k(g) = \max_{t \in I_k} \psi^{-1}(t) |g(t)|, \quad k \in \mathbb{N}.$$

Let F_1 be a Fréchet space of all continuous functions $g: \mathbb{R}_+ \rightarrow \mathbb{R}$ with a locally convex topology defined by systems of seminorms

$$p_{k_1}(g) = \max_{t \in I_k} |g(t)|_1, \quad k \in \mathbb{N},$$

where $|\cdot|_1$ means the absolute value in \mathbb{R} .

Let $\omega: \mathbb{R}_+ \rightarrow \mathbb{R}$ be a continuous function such that $\omega(0) = 0$ and $f: \mathbb{R}_+ \times C \rightarrow \mathbb{R}^n$ be a continuous function.

If $h \in C$, then denote $D_h = \{g \in D: g(t) = h(t), t \in \mathbb{R}_-\}$ with topology of locally uniformly convergence.

Denote $a^+ = \max\{a, 0\}$ for any $a \in \mathbb{R}$, $\text{sgn } 0 = 0$ and $\text{sgn } a = 1$ for $a > 0$.

If $g \in D$ and $u \in \mathbb{R}$, then g_u is the function defined for $s \in \mathbb{R}_-$ by $g_u(s) = g(u + s)$.

Let $Q: \mathbb{R} \rightarrow \mathbb{R}^{n \times n}$ be a continuous matrix function. Then Q_u denotes the matrix function defined by $Q_u(s) = Q(u + s)$ for $s \in \mathbb{R}_-$ and $u \in \mathbb{R}$. further, $Q_u g_u$, where $u \in \mathbb{R}$, is defined by $Q_u(s) g_u(s) = Q(u + s) g(u + s)$ for $s \in \mathbb{R}_-$. It is evident that for every $u \in \mathbb{R}$, $g_u \in C$, $Q_u g_u \in C$. Let $P: \mathbb{R}_+ \rightarrow \mathbb{R}^{n \times n}$ be a continuous matrix function.

We consider the following initial problem

$$(1) \quad x'(t) = P(t)f(t, Q_{\omega(t)}x_{\omega(t)})$$

$$(2) \quad x_0 = h,$$

where $h \in C$ is uniformly continuous in \mathbb{R}_- .

By solution of (1), (2) we understand any function $x: \mathbb{R} \rightarrow \mathbb{R}^n$ which is continuous on \mathbb{R} , $x(t) = h(t)$ for all $t \in \mathbb{R}_-$, x is differentiable on \mathbb{R}_+ and satisfies (1) everywhere on \mathbb{R}_+ .

Denote by X the set of all solutions of the initial problem (1), (2).

In the paper [1] an asymptotic properties of solutions of the equation (1) are studied in cases that (1) is a delay differential system. In the paper [2] an initial value problem for the functional differential equation with deviating argument $x'(t) = f(t, x_{\omega(t)})$ in Banach space is studied whereby the function f satisfies the Lipschitz condition. Further, the paper [2] deals with bounded solutions of an integral inequality with deviating argument.

The aim of this paper is to provide sufficient conditions for the existence of a solution $x \in X$ on \mathbb{R}_+ having some asymptotic properties. These results generalize the results of [1] and [2] where methods from [2] are applied.

We shall be employing the hypotheses:

$$(A_1) \quad \psi^{-1}(t) \int_0^t |P(s)f(s, 0)| ds < K_1 < \infty \quad \text{for } t \in \mathbb{R}_+,$$

$$(A_2) \quad |P(t)[f(t, Qz_1) - f(t, Qz_2)]| \leq \varphi(t, \|z_1 - z_2\|) \quad \text{for } t \in \mathbb{R}_+,$$

and for $z_1, z_2 \in C$, where $\varphi: \mathbb{R}_+ \times \mathbb{R}_+ \rightarrow \mathbb{R}_+$ is a locally integrable function on \mathbb{R}_+ for each fixed second argument and nondecreasing in the second argument for each fixed $t \in \mathbb{R}_+$,

$$(A_3) \quad \psi^{-1}(t) \int_0^t \varphi(s, c_1 + c_2 \operatorname{sgn} \omega^+(s) \psi[\omega^+(s)]) ds < K_2 < \infty,$$

for $t \in \mathbb{R}_+$ and any $c_1 \geq 0, c_2 \geq 0$,

$$(A_4) \quad \int_0^t |P(s)f(s, 0)| ds < \bar{K}_1 < \infty \quad \text{for } t \in \mathbb{R}_+,$$

$$(A_5) \quad \int_0^t \varphi(s, c_1 + c_2 \operatorname{sgn} \omega^+(s) \psi[\omega^+(s)]) \, ds < \bar{K}_2 < \infty,$$

for $t \in \mathbb{R}_+$ and any $c_1 \geq 0, c_2 \geq 0$.

Remark 1. It is evident that from the assumption (A_4) follows the assumption (A_1) and from (A_5) follows (A_3) . If, moreover, the function ψ is bounded on \mathbb{R}_+ then from (A_1) follows (A_4) and from (A_3) follows (A_5) .

Theorem 1. Let the assumptions (A_1) — (A_3) be satisfied. Then there exists a ψ — bounded solution $x \in X$ defined on \mathbb{R}_+ .

Proof. Let $\lambda \geq \psi^{-1}(0) \|h\| + K_1 + K_2$. Denote

$$M = \{g \in D_h : \psi^{-1}(t) |g(t)| \leq \lambda, \quad t \in \mathbb{R}_+\}.$$

It is evident that M is a convex closed set in D_h .

Define an operator T on M by

$$(3) \quad T(g)(t) = \begin{cases} h(t) & \text{for } t \in \mathbb{R}_- \\ h(0) + \int_0^t P(s) f(s, Q_{\omega(s)} g_{\omega(s)}) \, ds, & \text{for } t \in \mathbb{R}_+. \end{cases}$$

We show that $TM \subset M$.

If $t \in \mathbb{R}_-$, then $T(g)(t) = h(t)$.

If $t \in \mathbb{R}_+$, then with respect to (A_1) — (A_3) we get

$$\begin{aligned} |T(g)(t)| &\leq |h(0)| + \int_0^t |P(s) f(s, Q_{\omega(s)} g_{\omega(s)})| \, ds \leq |h(0)| + \\ &+ \int_0^t |P(s) f(s, 0)| \, ds + \int_0^t \varphi(s, \|g_{\omega(s)}\|) \, ds \leq |h(0)| + \\ &+ \int_0^t |P(s) f(s, 0)| \, ds + \int_0^t \varphi(s, \|h\| + \psi^{-1}(s) |g(s)| \operatorname{sgn} \omega^+(s) \psi[\omega^+(s)]) \, ds \leq \\ &\leq |h(0)| + \int_0^t |P(s) f(s, 0)| \, ds + \int_0^t \varphi(s, \lambda + \lambda \operatorname{sgn} \omega^+(s) \psi[\omega^+(s)]) \, ds, \end{aligned}$$

from which it follows

$$\begin{aligned} |\psi^{-1}(t) T(g)(t)| &\leq |\psi^{-1}(t) h(0)| + \psi^{-1}(t) \int_0^t |P(s) f(s, 0)| \, ds + \\ &+ \psi^{-1}(t) \int_0^t \varphi(s, \lambda + \lambda \operatorname{sgn} \omega^+(s) \psi[\omega^+(s)]) \, ds \leq \lambda. \end{aligned}$$

Further, we show that T is continuous on M . Let $\{g^n\}_{n=1}^\infty, g^n \in M$, be a

sequence converging uniformly to $g \in M$ on every compact interval $I_k \subset \mathbb{R}_+$. It is evident that with regard to the function ω , for every compact interval I_k there exists a compact interval I_l such that if $t \in I_k$, then $\omega(t) \in I_l$.

Let $\varepsilon > 0$ be an arbitrary number and I_k be a given compact interval. We show that on I_k we have

$$\psi^{-1}(t) T(g^n)(t) \rightrightarrows \psi^{-1}(t) T(g)(t).$$

Denote $m = \max_{t \in I_k} \psi^{-1}(t) = \psi^{-1}(0)$.

Let $g^n \rightrightarrows g$ for $t \in I_l$, where I_l is a compact interval corresponding to I_k . Since f is continuous and $g^n \rightrightarrows g$ on I_l , there exists a number $n_0 > 0$ such that for $n > n_0$ we have

$$(4) \quad |P(t)[f(t, Q_{\omega(t)} g^n_{\omega(t)}) - f(t, Q_{\omega(t)} g_{\omega(t)})]| < \frac{\varepsilon}{m \cdot k}, \quad t \in I_k.$$

Using (3) and (4), for $t \in I_k$ and $n > n_0$ we obtain

$$\begin{aligned} |T(g^n)(t) - T(g)(t)| &\leq \int_0^t |P(s)[f(s, Q_{\omega(s)} g^n_{\omega(s)}) - f(s, Q_{\omega(s)} g_{\omega(s)})]| ds < \\ &< \frac{\varepsilon}{m \cdot k} \int_0^t ds < \frac{\varepsilon \cdot k}{m \cdot k} = \frac{\varepsilon}{m}. \end{aligned}$$

From the last inequality for $t \in I_k$ it follows

$$p_k[T(g^n)(t) - T(g)(t)] < \frac{\varepsilon \cdot m}{m} = \varepsilon.$$

But this means that \overline{T} is continuous on M .

We show that \overline{TM} is a compact set. Now, from the fact that $TM \subset M$ it follows that, for the functions of TM , the functions $\psi^{-1}(t) T(g)(t)$ are uniformly bounded on \mathbb{R}_+ .

If $t_1, t_2 \in \mathbb{R}_+$, $t_1 < t_2$ are two arbitrary numbers, then we have the following estimate for T :

$$\begin{aligned} |\psi^{-1}(t_2) T(g)(t_2) - \psi^{-1}(t_1) T(g)(t_1)| &\leq |[\psi^{-1}(t_2) - \psi^{-1}(t_1)] h(0)| + \\ &+ \psi^{-1}(t_1) \int_{t_1}^{t_2} |P(s) f(s, 0)| ds + \psi^{-1}(t_1) \int_{t_1}^{t_2} \varphi(s, \lambda + \lambda \operatorname{sgn} \omega^+(s) \psi[\omega^+(s)]) ds. \end{aligned}$$

The right hand side of this inequality does not depend on g and therefore TM is a set of equicontinuous functions. Hence \overline{TM} is a compact set.

By Schauder—Tychonoff fixed point theorem, the operator T has a fixed point $g^* \in M$ and

$$g^*(t) = T(g^*)(t) = \begin{cases} h(t) & \text{for } t \in \mathbb{R}_- \\ h(0) + \int_0^t P(s)f(s, Q_{\omega(s)}g^*(s)) \, ds & \text{for } t \in \mathbb{R}_+. \end{cases}$$

Hence $g^* \in X$ and is ψ — bounded. This completes the proof.

Theorem 2. Let the assumptions (A_2) , (A_4) , (A_5) be satisfied. Then the set of ψ — bounded solutions $x \in X$ defined on \mathbb{R}_+ is non empty and for every such solution $x \in X$ there exists a constant vector $\alpha \in \mathbb{R}^n$ such that

$$(V) \quad \lim_{t \rightarrow \infty} \psi^{-1}(t)x(t) = \alpha.$$

Proof. Since the condition (A_4) implies the condition (A_1) and (A_5) implies (A_3) , from Theorem 1 we obtain that there exists a ψ — bounded solution $x \in X$ on \mathbb{R}_+ .

We show that (V) holds. Let $x \in X$ be a ψ — bounded solution defined on \mathbb{R}_+ . Then from (3) we get

$$(5) \quad \psi^{-1}(t)x(t) = \psi^{-1}(t)h(0) + \psi^{-1}(t) \int_0^t P(s)f(s, Q_{\omega(s)}x_{\omega(s)}) \, ds, \quad t \in \mathbb{R}_+.$$

Monotonicity of the function ψ on \mathbb{R}_+ implies the existence of the limit

$$(6) \quad \lim_{t \rightarrow \infty} \psi^{-1}(t)h(0),$$

and the condition (A_4) implies the existence of the limit

$$(7) \quad \lim_{t \rightarrow \infty} \psi^{-1}(t) \int_0^t P(s)f(s, 0) \, ds.$$

Similarly, from the condition (A_5) it follows that there exists the limit

$$(8) \quad \lim_{t \rightarrow \infty} \psi^{-1}(t) \int_0^t \varphi(s, \lambda + \lambda \operatorname{sgn} \omega^+(s) \psi[\omega^+(s)]) \, ds.$$

From the existence of limits (6), (7) and (8) it follows the existence of the limit

$$\lim_{t \rightarrow \infty} \psi^{-1}(t) \int_0^t P(s)f(s, Q_{\omega(s)}x_{\omega(s)}) \, ds.$$

Then from (5) we obtain that there exists $\lim_{t \rightarrow \infty} \psi^{-1}(t)x(t)$. Hence there exists $\alpha \in \mathbb{R}^n$ such that (V) is true. Thus the theorem is proved.

Theorem 3. Let $0 < q < 1$ and $p \in \mathbb{R}_+$ be arbitrary numbers. Let the function $\varrho: \mathbb{R}_+ \times \mathbb{R}_+ \rightarrow \mathbb{R}_+$ be locally integrable in the first argument and nondecreasing in the second argument and let for each $t \in \mathbb{R}_+$ and any $r \in \mathbb{R}_+$

$$(9) \quad \int_0^t \varrho(s, r) \, ds \leq qr + p.$$

Let $c \geq 0$ be a real number.

If $u(t) \geq 0$ is a real continuous solution of the inequality

$$(10) \quad u(t) \leq c + \int_0^t \varrho(s, u[\omega^+(s)]) \, ds, \quad t \in \mathbb{R}_+,$$

then there exists a real continuous solution $v = v(t, c)$ of the equation

$$(11) \quad v(t) = c + \int_0^t \varrho(s, v[\omega^+(s)]) \, ds, \quad t \in \mathbb{R}_+,$$

such that

$$(12) \quad u(t) \leq v(t, c)$$

is true for $t \in \mathbb{R}_+$.

Proof. Consider the Fréchet space F_1 . Let

$$(13) \quad \{T_1^m u(t)\}_{m=1}^\infty$$

be a sequence on F_1 , where

$$(14) \quad T_1^m u(t) = c + \int_0^t \varrho(s, T_1^{m-1} u[\omega^+(s)]) \, ds, \quad t \in \mathbb{R}_+.$$

We show that the operator T_1 is continuous on F_1 . Let $\{u^n\}_{n=1}^\infty, u^n \in F_1$ be a sequence and $v \in F_1$ such that

$$(15) \quad u^n \rightrightarrows v \quad \text{as } n \rightarrow \infty,$$

on every compact interval $I_k \subset \mathbb{R}_+$. Let $\varepsilon > 0$ be an arbitrary number and I_k be a given compact interval. Let I_l be a compact interval such that if $t \in I_k$ then $\omega(t) \in I_l$. Let (15) hold on I_l . Since ϱ is a continuous function and (15) hold on I_l , there exists a number $n_0 > 0$ such that for any $n > n_0$ we have

$$|\varrho(t, T_1 u^n[\omega^-(t)]) - \varrho(t, T_1 v[\omega^-(t)])|_1 < \frac{\varepsilon}{k}, \quad t \in I_k.$$

Then for $t \in I_k$ and $n > n_0$ we obtain

$$|T_1 u^n(t) - T_1 v(t)|_1 \leq \int_0^t [|\varrho(s, T_1 u^n[\omega^-(s)]) - \varrho(s, T_1 v[\omega^-(s)])|_1] \, ds < \frac{\varepsilon \cdot k}{k} = \varepsilon.$$

From the last inequality for $t \in I_k$ it follows

$$p_k [T_1 u^n(t) - T_1 v(t)] \rightarrow 0 \quad \text{as } n \rightarrow \infty.$$

Hence the operator T_1 is continuous on F_1 .

Let I_1 be a compact interval corresponding to the interval I_k in the sense as above. Since u is a continuous function on \mathbb{R}_+ , there exists a number $c_0 \in \mathbb{R}_+$ such that on I_1 the inequality

$$|u[\omega^+(t)]|_1 \leq c_0$$

is true.

Then from (14) with regard to (9) we get

$$\begin{aligned} |T_1^m u(t)|_1 &\leq c + \int_0^t \varrho(s, |T_1^{m-1} u[\omega^+(s)]|_1) ds \leq c + \int_0^t \varrho(s, c_{m-1}) ds \leq \\ &\leq c_m = a + qc_{m-1} \end{aligned}$$

for any $t \in I_k$ and any $m \in \mathbb{N}$, where $a = c + p$.

By using the principle of mathematical induction we can prove that

$$(16) \quad c_m = a + aq + aq^2 + \dots + aq^{m-1} + c_0 q^m.$$

From (16) one can see that

$$s_m = a + aq + aq^2 + \dots + aq^{m-1}$$

is the m -th partial sum of the geometric series

$$(17) \quad \sum_{m=1}^{\infty} aq^{m-1}$$

with the quotient $0 < q < 1$. Hence the series (17) converges to the sum $\frac{a}{1-q}$.

Then from (16) we get the following estimate

$$|c_m|_1 \leq \frac{a}{1-q} + c_0,$$

which implies that

$$|T_1^m u(t)|_1 \leq \frac{a}{1-q} + c_0.$$

But this means that the sequence (13) is uniformly bounded on every compact interval I_k .

Let $t_1, t_2 \in \mathbf{R}_+, t_1 < t_2$ be two arbitrary numbers. Then we obtain the following estimate

$$|T_1^m u(t_2) - T_1^m u(t_1)|_1 \leq \int_{t_1}^{t_2} \varrho(s, |T_1^{m-1} u[\omega^+(s)]|_1) ds \leq \int_{t_1}^{t_2} \varrho(s, K) ds,$$

where $K = \frac{a}{1-q} + c_0$.

The right hand side of this inequality does not depend on u and therefore the sequence (13) is a set of equicontinuous functions on I_k . Hence the sequence (13) is a compact set on every compact interval I_k .

In view of monotonicity of T_1 on F_1 , the inequality (10) implies that

$$u(t) \leq T_1 u(t) \leq T_1^2 u(t) \leq \dots \leq T_1^m u(t) \leq \dots$$

The compactness and monotonicity of the sequence (13) implies that the sequence (13) converges uniformly on every compact subinterval of \mathbf{R}_+ to some continuous function $v(t)$ and hence converges in the space F_1 to the element $v \in F_1$. From the continuity of the operator T_1 it follows that the function $v(t) = v(t, c)$ is a solution of the equation (11). hence (12) is true. This completes the proof.

If

$$(18) \quad \varrho(t, s) = n(t) v(s)$$

then Theorem 3 implies the following corollary.

Corollary 1. Let $0 < q < 1$ and $p \in \mathbf{R}_+$ be arbitrary numbers. Let $n: \mathbf{R}_+ \rightarrow \mathbf{R}_+$ be a locally integrable function on \mathbf{R}_+ such that the function

$$\int_0^r n(s) ds$$

is bounded on \mathbf{R}_+ . Let $v: \mathbf{R}_+ \rightarrow \mathbf{R}_+$ be a continuous and nondecreasing function such that for $r \in \mathbf{R}_+$

$$v(r) \leq qr + p.$$

Let $c \geq 0$ be a real number.

If $u(t) \geq 0$ is a real continuous solution of the inequality (10) (where ϱ is given in (18)), then there exists a real continuous solution $v = v(t, c)$ of the equation (11) on \mathbf{R}_+ such that (12) is true.

Remark 2. If $\varrho(t, s) = n(t)s$ then Theorem 3 is a special case of Lemma 3 in [2].

Denote $x \in X$ by $x(\dots, h)$.

Theorem 4. Assume that for the function $\varrho: \mathbf{R}_+ \times \mathbf{R}_+ \rightarrow \mathbf{R}_+$ the conditions

(A₂), (9) hold. Then for any $h_1, h_2 \in C$, h_1, h_2 are uniformly continuous on \mathbb{R}_- and $h_1(0) = h_2(0) = 0$ and for the solution x is true

$$(19) \quad \|x_t(\cdot, h_2) - x_t(\cdot, h_1)\| \leq v(t, \|h_2 - h_1\|) \quad \text{for } t \in \mathbb{R}_+,$$

where $v(t, \|h_2 - h_1\|)$ is the real continuous solution of (11) for $c = \|h_2 - h_1\|$.

Proof. Denote

$$u(t) = \sup_{-x < s \leq t} |x(s, h_2) - x(s, h_1)| = \|x_t(\cdot, h_2) - x_t(\cdot, h_1)\|, \quad t \in \mathbb{R}_+.$$

By (A₂) it follows that

$$|x(t, h_2) - x(t, h_1)| \leq |h_2(0) - h_1(0)| + \int_0^t \varrho(s, \|x_{\omega(s)}(\cdot, h_2) - x_{\omega(s)}(\cdot, h_1)\|) ds,$$

for $t \in \mathbb{R}_+$, which we have

$$u(t) \leq \|h_2 - h_1\| + \int_0^t \varrho(s, u[\omega^+(s)]) ds, \quad t \in \mathbb{R}_+.$$

Thus $u(t)$ satisfies (10) with $c = \|h_2 - h_1\|$. It is evident that $u(t)$ is a continuous function. The inequality (19) follows from Theorem 3. This completes the proof.

Next we shall consider the initial problem

$$(20) \quad y'(t) = A(t)y(t) + f(t, y_{\omega(t)})$$

$$(21) \quad y_+ = h,$$

where $A: \mathbb{R}_+ \rightarrow \mathbb{R}^{n \times n}$ is a continuous matrix function, and f, h have the same meaning as above.

Let Y be the set of all solutions of the initial problem (20), (21). Let $U(t)$ be a fundamental matrix for the system

$$(22) \quad u'(t) = A(t)u(t)$$

such that $U(0) = I$ denotes the identity matrix and $U^{-1}(t)$ is the inverse matrix to $U(t)$ on \mathbb{R}_+ .

Denote

$$P(t) = U^{-1}(t) \quad \text{and} \quad Q(t) = \begin{cases} U(t) & \text{for } t \in \mathbb{R}_+, \\ I & \text{for } t \in \mathbb{R}_-. \end{cases}$$

Theorem 5. Assume that for the matrices P, Q and the function f from (20) the hypotheses of Theorem 2 hold. Then the set of the solutions $y \in Y$ defined on \mathbb{R}_+ is non empty and for every such solution $y \in Y$ there exists a constant vector $\alpha \in \mathbb{R}^n$ such that

$$(23) \quad y(t) = Q(t)x(t) \quad \text{and} \quad \lim_{t \rightarrow -x} \psi^{-1}(t)x(t) = \alpha.$$

Proof. By the substitution

$$(24) \quad y(t) = Q(t)x(t)$$

we can transform every initial problem (20), (21) to the initial problem (1), (2), where $y_0 = x_0$. Relationship between sets X, Y is determined by (24).

From Theorem 1 and from (24) it follows that there exists a solution $y \in Y$ defined on \mathbb{R}_+ . From Theorem 2 moreover it follows that there exists a constant vector $\alpha \in \mathbb{R}^n$ such that (23) holds.

The above assertions imply the following corollaries.

Corollary 2. Assume that the hypotheses of Theorem 5 are satisfied and, furthermore, let $\lim_{t \rightarrow \infty} U(t)$ be a constant matrix. Then the set of ψ — bounded solutions $y \in Y$ defined on \mathbb{R}_+ is non empty and for every such solution $y \in Y$ it is true

$$(V') \quad \lim_{t \rightarrow \infty} \psi^{-1}(t)y(t) = \bar{\alpha}, \quad \bar{\alpha} \in \mathbb{R}^n.$$

Corollary 3. Assume that the hypotheses of Theorem 5 are satisfied and let all solutions of the system (22) be bounded on \mathbb{R}_+ . Let the function ψ be bounded on \mathbb{R}_+ . Then for each solution $y \in Y$ defined on \mathbb{R}_+ there exists a solution $u(t)$ of (22) on \mathbb{R}_+ such that

$$(25) \quad |y(t) - u(t)| \rightarrow 0 \quad \text{as } t \rightarrow \infty.$$

Proof. Since all solutions $u(t)$ of (22) are bounded on \mathbb{R}_+ , there exists a number $r > 0$ such that

$$|U(t)| \leq r \quad \text{for } t \in \mathbb{R}_+.$$

We know that if $a \in \mathbb{R}^n$ is a constant vector then the function $u(t) = U(t)a$ is a solution of (22).

Let $y \in Y$ be a solution defined on \mathbb{R}_+ . Theorem 5 implies that for the solution y there exists a constant vector $\alpha \in \mathbb{R}^n$ such that for $t \in \mathbb{R}_+$ (23) holds. Consider the solution $u(t)$ of (22) in the form $u(t) = U(t)\alpha$. Then we get

$$|y(t) - u(t)| = |U(t)x(t) - U(t)\alpha| \leq |U(t)||x(t) - \alpha| \leq r|x(t) - \alpha| \rightarrow 0,$$

as $t \rightarrow \infty$, which is (25).

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SÚHRN

O ASYMPTOTICKOM CHOVANÍ RIEŠENÍ FUNKCIONÁLNO-DIFERENCIÁLNYCH ROVNÍC S POSUNUTÝM ARGUMENTOM

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V práci sú uvedené postačujúce podmienky pre to, aby existovalo ψ — ohraničené riešenie funkcionálno-diferenciálnej rovnice s posunutým argumentom tvaru $x'(t) = P(t)f(t, Q_{\alpha(t)}x_{\alpha(t)})$ a navyše, aby toto riešenie malo isté asymptotické vlastnosti.

РЕЗЮМЕ

ОБ АСИМПТОТИЧЕСКОМ ПОВЕДЕНИИ РЕШЕНИЙ ФУНКЦИОНАЛЬНО-ДИФФЕРЕНЦИАЛЬНЫХ УРАВНЕНИЙ С ОТКЛОНЯЮЩИМСЯ АРГУМЕНТОМ

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В работе приведены достаточные условия для того, чтобы существовало ψ — ограниченное решение функционально-дифференциального уравнения с отклоняющимся аргументом $x'(t) = P(t)f(t, Q_{\alpha(t)}x_{\alpha(t)})$ и, кроме того, чтобы это решение имело какие-то асимптотические свойства.

